

STATS 217: Introduction to Stochastic Processes I

Lecture 15

Period of a state

- Let P be the transition matrix of a DTMC on S .
- For a state $x \in S$, let

$$\mathcal{T}(x) := \{t \geq 1 : P_{x,x}^t > 0\}$$

denote the set of times when it is possible for the chain to return to its starting position x .

Period of a state

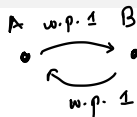
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denote the set of times when it is possible for the chain to return to its starting position x .

- The **period** of $x \in S$ is defined to be the greatest common divisor (gcd) of $\mathcal{T}(x)$.

Example



Two-state Markov chain with the transition matrix

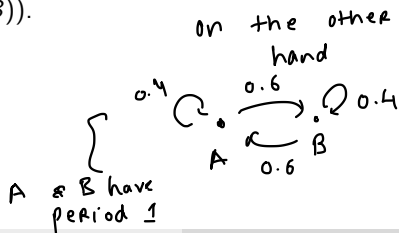
$$P = \begin{bmatrix} & A & B \\ A & 0 & 1 \\ B & 1 & 0 \end{bmatrix}$$

Example

Two-state Markov chain with the transition matrix

$$P = \begin{bmatrix} & A & B \\ A & 0 & 1 \\ B & 1 & 0 \end{bmatrix}$$

- $\mathcal{T}(A) = \{2, 4, 6, 8, \dots\}$ and $\mathcal{T}(B) = \{2, 4, 6, 8, \dots\}$.
- Hence, $\gcd(\mathcal{T}(A)) = 2 = \gcd(\mathcal{T}(B))$.



Periodicity is a class property

$$x \leftrightarrow y$$

Recall this means that

$$p_{x,y}^k > 0; \quad p_{y,x}^r > 0$$

- In the previous example, the chain is irreducible and both states have the same period.
- This is true in general i.e. if P is irreducible, then $\gcd(T(x)) = \gcd(T(y))$ for all $x, y \in S$.

consequence: for \mathbb{I} irreducible,
makes sense to talk
about the period of \mathbb{I} .

•

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- To see this, fix $x, y \in S$. By irreducibility, we can find $r, \ell \geq 0$ such that $P_{x,y}^r > 0$ and $P_{y,x}^\ell > 0$.

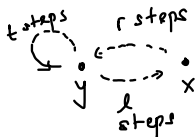
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- For this, note that if $t \in \mathcal{T}(y)$, then we must have that $t + (r + \ell) \in \mathcal{T}(x)$.
- Therefore,

$$\underline{\underline{\mathcal{T}(y)}} \subseteq \underline{\underline{\mathcal{T}(x) - (r + \ell)}}.$$



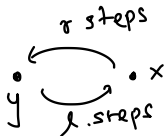
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- Therefore,

$$\mathcal{T}(y) \subseteq \mathcal{T}(x) - \underbrace{(r + \ell)}.$$

- Moreover, we have $(r + \ell) \in \mathcal{T}(x)$.

$$\cap \mathcal{T}(y)$$



Periodicity is a class property

- $\gcd(A)$ divides ^{all} $a \in A$
- it is the largest such integer.

- Therefore, every element of $\mathcal{T}(x) - (r + \ell)$ is divisible by $\gcd(\mathcal{T}(x))$.

$$\{ \overset{\text{"}}{t} - (r + \ell) : t \in \mathcal{T}(x) \}$$

Periodicity is a class property

- Therefore, every element of $\mathcal{T}(x) - (r + \ell)$ is divisible by $\gcd(\mathcal{T}(x))$.
- Hence, every element of $\mathcal{T}(y)$ is divisible by $\gcd(\mathcal{T}(x))$, so that, by definition of the gcd, we have

$$\swarrow \quad \gcd(\mathcal{T}(x)) \leq \gcd(\mathcal{T}(y)).$$

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- Interchanging the roles of x, y , we see that $\gcd(\mathcal{T}(y)) \leq \gcd(\mathcal{T}(x))$ as well, which shows that x and y have the same period.
- In fact, the same argument as above shows that if $x \leftrightarrow y$ are two communicating states in S , then

$$\gcd(\mathcal{T}(x)) = \gcd(\mathcal{T}(y)).$$

Aperiodicity

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Aperiodicity

- Let P be the transition matrix of an irreducible DTMC on S .
- We say that P is **aperiodic** if the period of some state (and hence, all states) is 1.
- In practice, aperiodicity is not a serious restriction. For instance, if P is an irreducible transition matrix with the unique stationary distribution π , then

$$P' = \frac{1}{2}P + \frac{1}{2}I \rightarrow \left(|S| \times |S| \text{ identity matrix} \right)$$

is clearly an irreducible, aperiodic, transition matrix with the unique stationary distribution π .

- P' is called the **lazy version** of P .

$$\begin{aligned} \pi P' &= \frac{1}{2} \pi P + \frac{1}{2} \pi I \\ &= \frac{1}{2} \pi + \frac{1}{2} \pi \end{aligned}$$

Convergence theorem

Next week, we will prove the following theorem, which is often called the **Fundamental theorem of Markov Chains**.

theorem

Let P be an irreducible and aperiodic transition matrix on a finite state space S . Then, P has a unique stationary distribution π and moreover, for any $x \in S$,

$$P_{x,y}^t \rightarrow \pi(y) \quad \text{as } t \rightarrow \infty.$$

"

$$\mathbb{P}[X_t = y \mid X_0 = x]$$

$$X_0, X_1, X_2, X_3, \dots, X_t, X_{t+1}, \dots$$

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For the rest of this week, we will explore some applications of this theorem.

Markov chain Monte Carlo (MCMC)

- A fundamental computational task in many applications is to sample from a given distribution π on a finite set S .

right now, this has
nothing to do w/
Markov chains.

Markov chain Monte Carlo (MCMC)

- A fundamental computational task in many applications is to sample from a given distribution π on a finite set S .
- Given the convergence theorem, the following is a natural approach: construct an irreducible, aperiodic transition matrix on S with stationary distribution π . Simulate a DTMC $(X_n)_{n \geq 0}$ with transition matrix P and starting from $X_0 = x$ (for some $x \in S$). Output X_t for 'sufficiently large' t .

algorithmically (rigorous sense)

* find P

* you have some error tolerance ϵ .

hard part \rightarrow * prove a thm upper bounding
 t in terms of ϵ .

* run the chain for t steps; return X_t

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- By the convergence theorem,

$$\mathbb{P}[X_t = y \mid X_0 = x] = P_{x,y}^t \rightarrow \pi(y),$$

so that X_t has distribution approximately equal to π when t is sufficiently large.

Markov chain Monte Carlo (MCMC)

- Given a probability distribution π on S , how can we construct an irreducible and aperiodic transition matrix with stationary distribution π ?

main criterion: convergence
↓ happens quickly

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- Given a probability distribution π on S , how can we construct an irreducible and aperiodic transition matrix with stationary distribution π ?
- In fact, in many applications, we are not given $\pi(x)$, but only $\tilde{\pi}(x) = \pi(x) \cdot Z$ for an unknown (and computationally intractable) constant Z .

$$\pi(x) = \frac{\tilde{\pi}(x)}{Z}$$

$$\text{since } \sum_x \pi(x) = 1 \Rightarrow Z = \sum_x \tilde{\pi}(x)$$

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- As an example, consider Markov random fields (undirected graphical models). Here, we are given an undirected graph $G = (V, E)$ and the state space S is (for instance)

$$S = \{-1, 1\}^V$$

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i.e. there is a variable assigned to each vertex of the graph, which can take on the values ± 1 .

- We will denote the number of vertices $|V|$ by n .

The Ising model

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- For instance, for the so-called **ferromagnetic Ising model**, this is given by the function $H : \{\pm 1\}^n \rightarrow \mathbb{R}$, where

$$H(x_1, \dots, x_n) = - \sum_{uv \in E} x_u x_v - h \sum_{v \in V} x_v,$$

where h is a parameter known as the external field.

“lower energy” is “more stable”

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this is
a modeling
thing.

where h is a parameter known as the external field.

- So, the energy will be lower if neighboring vertices have the same value and if vertices have the same sign as the external field.

The Ising model

- The corresponding **Gibbs distribution/Boltzmann distribution**, whose form is motivated by the principle of maximum entropy, is given by

$$\pi(x) := \exp(-\beta H(x)) / Z,$$

where $\beta \geq 0$ is called the **inverse temperature** and Z is a normalizing constant called the **partition function**.

more stable state $\rightarrow H(x)$ is smaller
 $\rightarrow -H(x)$ is larger
 $\rightarrow \pi(x)$ is larger.

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- Explicitly,

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which is a sum of exponentially many terms.

- In general, Z is computationally intractable (under standard assumptions in computational complexity theory).

The Ising model

- Since Z is computationally intractable, we essentially have access to the function $\tilde{\pi} : \{-1, 1\}^n \rightarrow \mathbb{R}^{\geq 0}$ given by

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$$H(x) = - \sum_{u,v} x_u x_v \quad \begin{array}{l} \text{the smallest } I \text{ can make this} \\ \text{is to make } x_u x_v = 1 \end{array}$$

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- In particular, for the ferromagnetic Ising model with zero external field $h = 0$, the states with the highest probability are $(1, \dots, 1)$ and $(-1, \dots, -1)$.
- As $\beta \rightarrow \infty$, π converges to the uniform distribution on $(1, \dots, 1) \cup (-1, \dots, -1)$.

H_{\max}

$H_{\max} - 0.01$

$$\pi(x) = \frac{\exp(-\beta H(x))}{\sum \exp(-\beta H(x))}$$

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- As $\beta \rightarrow \infty$, π converges to the uniform distribution on $(1, \dots, 1) \cup (-1, \dots, -1)$. i.e. $\mathbb{P}[(1, \dots, 1)] = \mathbb{P}[-1, \dots, -1] = 1/2$.
- On the other hand, for $\beta = 0$, π is simply the uniform distribution on the entire discrete hypercube $\{-1, 1\}^n$.

$$\beta H(x) = 0$$

The Metropolis chain

- Now, suppose that we are given a probability distribution π on S with $\pi(x) > 0$ for all $x \in S$. Possibly, we are not given π , but rather $\tilde{\pi}$, with $\tilde{\pi} = \pi \cdot Z$ for some unknown constant Z .

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- Next time, we will see the **Metropolis chain**, which provides a very general way to construct a transition matrix P with stationary distribution π .
- Moreover, the transition matrix only depends on $\tilde{\pi}$ and not π , which as we have seen, is a very important consideration.